

III. Structural inference from VAR's

A. Recursive structural models

Consider simple structural model

y_{1t} = real GDP growth

y_{2t} = inflation

y_{3t} = fed funds rate

y_{4t} = rate of growth of M2

(1) aggregate spending responds to shocks only with a 1-quarter delay:

$$y_{1t} = k_1 + \mathbf{b}_1^{(1,\cdot)'} \mathbf{y}_{t-1} + \mathbf{b}_2^{(1,\cdot)'} \mathbf{y}_{t-2} + \dots + \mathbf{b}_p^{(1,\cdot)'} \mathbf{y}_{t-p} + u_{1t}$$

(2) Phillips curve is relation between current output growth and inflation and lags of all variables:

$$y_{2t} = k_2 + b_0^{(2,1)} y_{1t} + \mathbf{b}_1^{(2,\cdot)'} \mathbf{y}_{t-1} + \mathbf{b}_2^{(2,\cdot)'} \mathbf{y}_{t-2} + \dots + \mathbf{b}_p^{(2,\cdot)'} \mathbf{y}_{t-p} + u_{2t}$$

(3) Fed sets the funds rate in response to current output and inflation and lags of all variables:

$$y_{3t} = k_3 + b_0^{(3,1)} y_{1t} + b_0^{(3,2)} y_{2t} + \mathbf{b}_1^{(3,\cdot)'} \mathbf{y}_{t-1} + \mathbf{b}_2^{(3,\cdot)'} \mathbf{y}_{t-2} + \dots + \mathbf{b}_p^{(3,\cdot)'} \mathbf{y}_{t-p} + u_{3t}$$

Key question of interest: if Fed decided to set u_{3t} higher than it usually does, what will be the effects?

$$\hat{\partial} \mathbf{y}_{t+s} / \partial u_{3t}$$

(4) Money demand depends on current output, inflation, and interest rate:

$$y_{4t} = k_4 + b_0^{(4,1)}y_{1t} + b_0^{(4,2)}y_{2t} + b_0^{(4,3)}y_{3t} + \mathbf{b}_1^{(4,\cdot)'}\mathbf{y}_{t-1} + \mathbf{b}_2^{(4,\cdot)'}\mathbf{y}_{t-2} + \dots + \mathbf{b}_p^{(4,\cdot)'}\mathbf{y}_{t-p} + u_{4t}$$

Stack these 4 equations into a vector dynamic structural model:

$$\mathbf{B}_0\mathbf{y}_t = \mathbf{k} + \mathbf{B}_1\mathbf{y}_{t-1} + \mathbf{B}_2\mathbf{y}_{t-2} + \dots + \mathbf{B}_p\mathbf{y}_{t-p} + \mathbf{u}_t$$

where

$$\mathbf{k} = (k_1, k_2, k_3, k_4)'$$

$$\mathbf{B}_j = \begin{bmatrix} \mathbf{b}_j^{(1,\cdot)'} \\ \mathbf{b}_j^{(2,\cdot)'} \\ \mathbf{b}_j^{(3,\cdot)'} \\ \mathbf{b}_j^{(4,\cdot)'} \end{bmatrix} \quad (4 \times 4)$$

$$\mathbf{B}_0 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -b_0^{(2,1)} & 1 & 0 & 0 \\ -b_0^{(3,1)} & -b_0^{(3,2)} & 1 & 0 \\ -b_0^{(4,1)} & -b_0^{(4,2)} & -b_0^{(4,3)} & 1 \end{bmatrix}$$

Note we can assume without loss of generality that \mathbf{u}_t is serially uncorrelated.

For example, suppose

$$\mathbf{B}_0\mathbf{y}_t = \mathbf{k} + \mathbf{B}_1\mathbf{y}_{t-1} + \mathbf{u}_t$$

where $\mathbf{u}_t \sim VAR(1)$

$$\mathbf{u}_t = \mathbf{A}\mathbf{u}_{t-1} + \mathbf{u}_t^*$$

$$\mathbf{B}_0\mathbf{y}_t - \mathbf{A}\mathbf{B}_0\mathbf{y}_{t-1} = (\mathbf{I} - \mathbf{A})\mathbf{k}$$

$$+ \mathbf{B}_1\mathbf{y}_{t-1} - \mathbf{A}\mathbf{B}_1\mathbf{y}_{t-2} + \mathbf{u}_t^*$$

$$\mathbf{B}_0\mathbf{y}_t = \mathbf{k}^* + \mathbf{B}_1^*\mathbf{y}_{t-1} + \mathbf{B}_2^*\mathbf{y}_{t-2} + \mathbf{u}_t^*$$

We can also linearize to approximate any dynamic structural model as something of the form

$$\mathbf{B}_0\mathbf{y}_t = \mathbf{k} + \mathbf{B}_1\mathbf{y}_{t-1} + \mathbf{B}_2\mathbf{y}_{t-2} + \dots + \mathbf{B}_p\mathbf{y}_{t-p} + \mathbf{u}_t$$

But it would be a special model if

\mathbf{B}_0 had the particular triangular structure posited above

$$\mathbf{B}_0 \mathbf{y}_t = \mathbf{k} + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t$$

But if we premultiply by \mathbf{B}_0^{-1} ,

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \varepsilon_t$$

$$\mathbf{c} = \mathbf{B}_0^{-1} \mathbf{k}$$

$$\Phi_j = \mathbf{B}_0^{-1} \mathbf{B}_j$$

$$\varepsilon_t = \mathbf{B}_0^{-1} \mathbf{u}_t$$

Conclusion: any dynamic structural model of the form

$$\mathbf{B}_0 \mathbf{y}_t = \mathbf{k} + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t$$

with \mathbf{u}_t serially uncorrelated implies a VAR of the form

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \varepsilon_t$$

with ε_t serially uncorrelated

So VAR is just another representation of the structural model

If we knew the structural parameters ($\mathbf{B}_0, \mathbf{B}_1, \dots$) and shocks (\mathbf{u}_t) we could calculate the VAR parameters (Φ_1, Φ_2, \dots) and innovations (ε_t)

Any question about the structural model has an analog in an observable property of the VAR, e.g.

$$\frac{\partial \mathbf{y}_{t+m}}{\partial \mathbf{u}_t'} = \frac{\partial \mathbf{y}_{t+m}}{\partial \varepsilon_t'} \frac{\partial \varepsilon_t}{\partial \mathbf{u}_t'} = \Psi_m \mathbf{B}_0^{-1}$$

Does this mean that if we knew the VAR parameters we could infer the structural magnitudes?

Answer: no

VAR parameters:

$$\mathbf{c}, \Phi_1, \Phi_2, \dots, \Phi_p, E(\varepsilon_t \varepsilon_t')$$

$$= n + n^2 p + n(n+1)/2$$

Structural parameters:

$$\mathbf{k}, \mathbf{B}_0, \mathbf{B}_1, \dots, \mathbf{B}_p, E(\mathbf{u}_t \mathbf{u}_t')$$

$$= n + n^2(p+1) + n(n+1)/2$$

Need restrictions, e.g.

$$E(\mathbf{u}_t \mathbf{u}_t') = \text{diagonal}$$

zeros in \mathbf{B}_0

In fact, the earlier triangular model would work perfectly:

$$\mathbf{B}_0 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -b_0^{(2,1)} & 1 & 0 & 0 \\ -b_0^{(3,1)} & -b_0^{(3,2)} & 1 & 0 \\ -b_0^{(4,1)} & -b_0^{(4,2)} & -b_0^{(4,3)} & 1 \end{bmatrix}$$

In a case like this one where there is a one-to-one mapping from VAR parameters to structural parameters, we can find the MLE of the latter from the appropriate transformations of the usual VAR estimates.

Structural model:

$$\mathbf{B}_0 \mathbf{y}_t = \mathbf{b}_0 + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t$$

$$E(\mathbf{u}_t \mathbf{u}_t') = \mathbf{D} \text{ (diagonal)}$$

VAR:

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

$$E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t') = \boldsymbol{\Omega}$$

$$\boldsymbol{\varepsilon}_t = \mathbf{B}_0^{-1} \mathbf{u}_t$$

$$\boldsymbol{\Omega} = \mathbf{B}_0^{-1} \mathbf{D} (\mathbf{B}_0^{-1})'$$

$$\boldsymbol{\Omega} = \mathbf{B}_0^{-1} \mathbf{D} (\mathbf{B}_0^{-1})'$$

One way to find:

$$\hat{\boldsymbol{\Omega}} = T^{-1} \sum_{t=1}^T \hat{\boldsymbol{\varepsilon}}_t \hat{\boldsymbol{\varepsilon}}_t'$$

If \mathbf{B}_0 is lower triangular, so is \mathbf{B}_0^{-1}

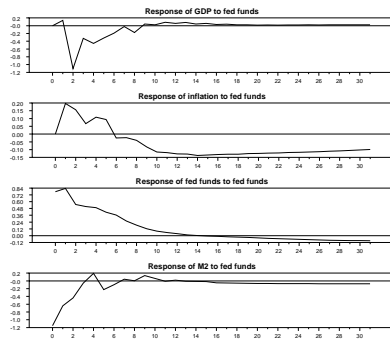
want triangular factorization of $\hat{\boldsymbol{\Omega}}$

(= Cholesky decomposition)

In other words, the answer to the forecasting question we asked earlier,

$$\frac{\partial E(\mathbf{y}_{t+s} | y_{1t}, y_{2t}, y_{3t}, \mathbf{y}_{t-1}, \mathbf{y}_{t-2}, \dots, \mathbf{y}_{t-p})}{\partial y_{3t}}$$

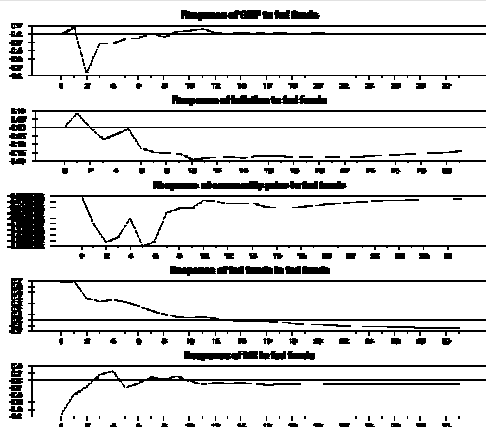
which we found by using the %sigma specification in the RATS impulse command with fed funds ordered third, is the same as the answer to the structural question $\partial \mathbf{y}_{t+s} / \partial u_{3t}$, which gave the dynamic effects of a shock to monetary policy.



- “Price puzzle”: when the Fed tightens, it “causes” higher inflation
- Empirical basis: if the Fed raises funds rate higher than we would expect given current GDP and inflation, it causes us to revise upward our forecast of future inflation

- Plausible interpretation: the Fed raised rates in *anticipation* of higher future inflation
- Possible solution: we need to include in the Fed’s behavioral equation the variables on which the Fed is basing its forecast of future inflation
- One common proxy: commodity price index

- *Example 9: Using index of sensitive materials prices to resolve the price puzzle
- open data psm99q_qtr.txt
- data(org=obs) 1948:1 2004:1 date3 ppi
- set ppich = 400*log(ppi(t)/ppi(t-1))
- system(model=basemod)
- variables gdpch inflation ppich fedfunds mgrow
- lags 1 to 5
- det constant
- end(system)



Things we can now calculate:
 (1) effect of any structural shock on any variable s periods later:

$$\frac{\partial \mathbf{y}_{t+s}}{\partial \mathbf{u}_t} = \Psi_s \mathbf{A}$$

Things we can now calculate:
 (2) size of any structural shock
 in any observed period

$$\hat{\mathbf{u}}_t = \hat{\mathbf{B}}_0 \hat{\boldsymbol{\varepsilon}}_t = \hat{\mathbf{A}}^{-1} \hat{\boldsymbol{\varepsilon}}_t$$

Things we can now calculate:
 (3) Importance of k th structural shock in accounting for s -period-ahead variance of $y_{i,t+s}$

Row i , column k element of

$$\sum_{m=0}^{s-1} \boldsymbol{\Psi}_m (\mathbf{a}_k \mathbf{a}_k' d_k) \boldsymbol{\Psi}_m'$$

The above assumed that commodity prices don't enter the Phillips Curve ($b_0^{(2,3)} = 0$). What if they do?

The above assumed that commodity prices don't enter the Phillips Curve ($b_0^{(2,3)} = 0$). What if they do?

No problem, as long as interest rate does not ($b_0^{(2,4)} = 0$).

$$\mathbf{B}_0 = \begin{bmatrix} x & x & x & 0 & 0 \\ x & x & x & 0 & 0 \\ x & x & x & 0 & 0 \\ x & x & x & x & 0 \\ x & x & x & x & x \end{bmatrix}$$

In this model, the parameters of first three equations and effect of first three shocks is unidentified, but effect of monetary policy shock still is.

Another way to say this: if what we care about is only the effect of variable q , it does not matter how we order variables $1, 2, \dots, q-1$ or $q+1, q+2, \dots, n$

III. Structural inference from VAR's

- A. Recursive structural models
- B. Nonrecursive structural models

VAR (reduced-form)

$\mathbf{y}_t = (n \times 1)$ vector

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

$$\boldsymbol{\varepsilon}_t = \mathbf{y}_t - \hat{\mathbf{y}}_{t|t-1}$$

$$E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t') = \boldsymbol{\Omega}$$

Structural model:

$$\mathbf{B}_0 \mathbf{y}_t = \mathbf{b}_0 + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t$$

$$E(\mathbf{u}_t \mathbf{u}_{t-m}') = \begin{cases} \mathbf{D} & \text{for } m = 0 \\ \mathbf{0} & \text{for } m \neq 0 \end{cases}$$

Relation between the two: premultiply structural model by \mathbf{B}_0^{-1} :

$$\mathbf{B}_0 \mathbf{y}_t = \mathbf{b}_0 + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t$$

$$\mathbf{y}_t = \mathbf{B}_0^{-1} \mathbf{b}_0 + \mathbf{B}_0^{-1} \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_0^{-1} \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_0^{-1} \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{B}_0^{-1} \mathbf{u}_t$$

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

$$\mathbf{y}_t = \mathbf{B}_0^{-1} \mathbf{b}_0 + \mathbf{B}_0^{-1} \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_0^{-1} \mathbf{B}_2 \mathbf{y}_{t-2} + \dots + \mathbf{B}_0^{-1} \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{B}_0^{-1} \mathbf{u}_t$$

$$\mathbf{y}_t = \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots + \Phi_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t$$

Can estimate reduced-form by OLS regressions

Goal: put enough restrictions on $\mathbf{D}, \mathbf{B}_0, \mathbf{B}_1, \dots, \mathbf{B}_p$ so that there is unique mapping from easily estimated parameters $(\boldsymbol{\Omega}, \Phi_1, \Phi_2, \dots, \Phi_p)$ into desired parameters $(\mathbf{D}, \mathbf{B}_0, \mathbf{B}_1, \dots, \mathbf{B}_p)$

Typical approach:

$\mathbf{B}_1, \mathbf{B}_2, \dots, \mathbf{B}_p$ unrestricted

$$E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t') = \boldsymbol{\Omega}$$

$$\mathbf{B}_0^{-1} \mathbf{u}_t = \boldsymbol{\varepsilon}_t$$

$$E(\mathbf{u}_t \mathbf{u}_t') = \mathbf{D}$$

$$\Rightarrow E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t') = \mathbf{B}_0^{-1} \mathbf{D} (\mathbf{B}_0^{-1})'$$

Goal: find $\hat{\mathbf{B}}_0$ and $\hat{\mathbf{D}}$ satisfying restrictions such that

$$\hat{\mathbf{B}}_0^{-1} \hat{\mathbf{D}} (\hat{\mathbf{B}}_0^{-1})' = \hat{\boldsymbol{\Omega}}$$

$$\hat{\boldsymbol{\Omega}} = T^{-1} \sum_{t=1}^T \hat{\boldsymbol{\varepsilon}}_t \hat{\boldsymbol{\varepsilon}}_t'$$

$\hat{\boldsymbol{\Omega}}$ has $n(n+1)/2$ distinct elements
so can have $n(n+1)/2$ unknowns
in \mathbf{B}_0 and \mathbf{D}

One way to find: maximize log likelihood by numerical search

$$\max (T/2) \log |\mathbf{B}_0|^2 - (T/2) \log |\mathbf{D}| \\ - (T/2) \text{trace} \{ \mathbf{B}_0' \mathbf{D}^{-1} \mathbf{B}_0 \hat{\boldsymbol{\Omega}} \}$$

optimal values will satisfy

$$\hat{\mathbf{B}}_0^{-1} \hat{\mathbf{D}} (\hat{\mathbf{B}}_0^{-1})' = \hat{\boldsymbol{\Omega}}$$

$\boldsymbol{\varepsilon}_t$ = VAR forecast errors

\mathbf{u}_t = true structural disturbances

$$\boldsymbol{\varepsilon}_t = \mathbf{B}_0^{-1} \mathbf{u}_t$$

$\partial \mathbf{y}_{t+s} / \partial \boldsymbol{\varepsilon}_t' = \boldsymbol{\Psi}_s$ is known

$\partial \mathbf{y}_{t+s} / \partial \mathbf{u}_t'$ is desired

$$\partial \mathbf{y}_{t+s} / \partial \mathbf{u}_t' = \boldsymbol{\Psi}_s \mathbf{B}_0^{-1}$$

- Implement with RATS cvmodel command
- Example 10: Implementing the recursive Cholesky factorization by hand

- system(model=basemod)
- variables gdpch
inflation ppich
fedfunds mgrow
- lags 1 to 5
- det constant
- end(system)
- estimate

- system(model= basemod)
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inflation ppich
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- end(system)
- estimate

%sigma is now VAR
residual variance-covariance

$$\hat{\Omega} = \mathbf{T}^{-1} \sum_{t=1}^T \hat{\epsilon}_t \hat{\epsilon}_t'$$

- nonlin a21 a31 a32 a41 a42 a43 a51
a52 a53 a54
- dec frm|rect| afm|
- frm| afm| = || 1.0, 0.0, 0.0, 0.0, 0.0 |\$
- a21, 1.0, 0.0, 0.0, 0.0 |\$
- a31, a32, 1.0, 0.0, 0.0 |\$
- a41, a42, a43, 1.0, 0.0 |\$
- a51, a52, a53, a54, 1.0 ||
- compute a21 = a31 = a32 = a41 = a42
= a43 = a51 = a52 = a53 = a54 = 0
- cvmodel(iters=100,method=bfgs,trace,
factor=afactor) %sigma afm|

- nonlin a21 a31 a32 a41 a42 a43 a51
a52 a53 a54
- dec frm|rect| afm|
- frm| afm| = || 1.0, 0.0, 0.0, 0.0, 0.0 |\$
- a21, 1.0, 0.0, 0.0, 0.0 |\$
- a31, a32, 1.0, 0.0, 0.0 |\$
- a41, a42, a43, 1.0, 0.0 |\$
- a51, a52, a53, a54, 1.0 ||
- compute a21 = a31 = a32 = a41 = a42
= a43 = a51 = a52 = a53 = a54 = 0
- cvmodel(iters=100,method=bfgs,trace,
factor=afactor) %sigma afm|

a21, a31, ... are now values
that maximize

$$(T/2) \log |\mathbf{B}_0|^2 - (T/2) \log |\mathbf{D}| \\ - (T/2) \text{trace} \{ \mathbf{B}_0' \mathbf{D}^{-1} \mathbf{B}_0 \hat{\Omega} \}$$

- compute aest = || 1.0, 0.0, 0.0, 0.0, 0.0
|\$
- a21, 1.0, 0.0, 0.0, 0.0 |\$
- a31, a32, 1.0, 0.0, 0.0 |\$
- a41, a42, a43, 1.0, 0.0 |\$
- a51, a52, a53, a54, 1.0 ||
- compute aest = inv(aest)

- compute aest = || 1.0, 0.0, 0.0, 0.0, 0.0
|\$
- a21, 1.0, 0.0, 0.0, 0.0 |\$
- a31, a32, 1.0, 0.0, 0.0 |\$
- a41, a42, a43, 1.0, 0.0 |\$
- a51, a52, a53, a54, 1.0 ||
- compute aest = inv(aest)

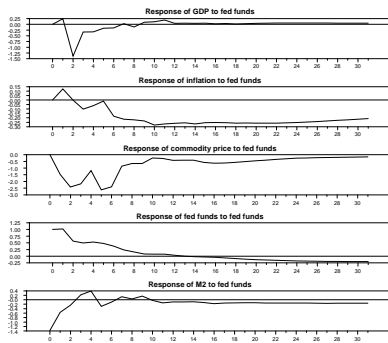
aest is now $\hat{\mathbf{B}}_0^{-1}$

Plots of $\partial \mathbf{y}_{t+s} / \partial \mathbf{u}_t' = \hat{\Psi}_s \hat{\mathbf{B}}_0^{-1}$
are now obtained as follows:

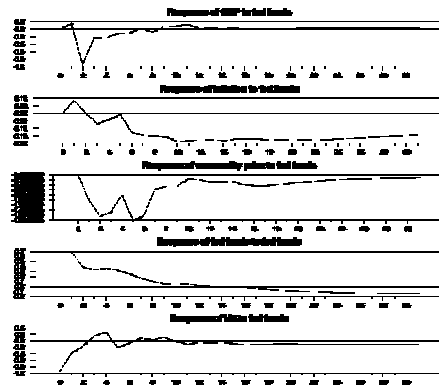
- compute neqn = 5
- compute nsteps = 32
- declare vect[labels] implabel(neqn)
- compute implabel=|| 'GDP', 'inflation', 'commodity price', 'fed funds', 'M2' ||
- declare rect[series] impblk(neqn,1)

- smpl 1 nsteps
- do j=1,neqn
- impulse(model=basemod, shock=%xcol(aest,j), result=impblk) neqn nsteps
- spgraph(vfields=neqn)
- do i=1,neqn
- compute graphlabel='Response of ' +implabel(i) + ' to ' +implabel(j)
- graph(header=graphlabel,nodates,number=0) 1
- # impblk(i,1)
- end do i
- spgraph(done)
- end do j

Example 10: IRF from recursive nonlinear estimation



Example 9: IRF from Cholesky factorization

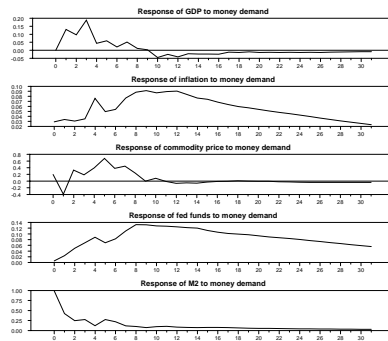
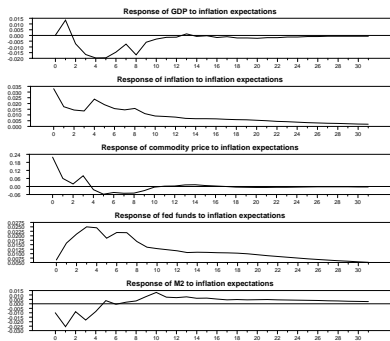
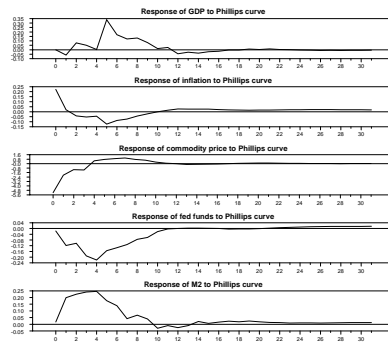
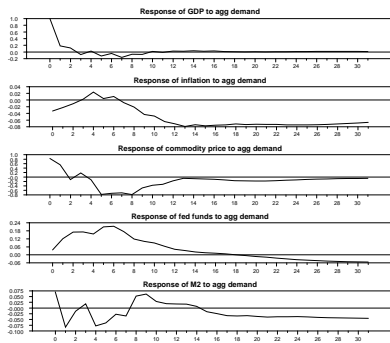
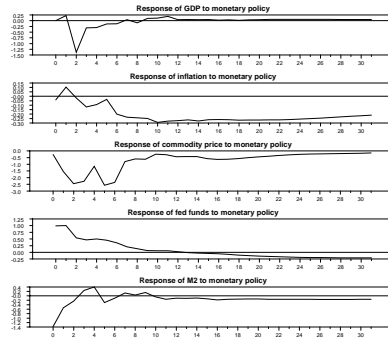


Example 11: nonrecursive structure

- (1) Aggregate demand responds to variables only with a lag
- (2) Phillips curve includes commodity price (inflationary expectations)
- (3) Inflation expectations respond to current inflation and money growth
- (4) Fed responds to output, inflation, and commodity price
- (5) Money demand does not depend on commodity price

	GDP	inflation	com price	fed funds	M2
aggregate demand	x	0	0	0	0
Phillips curve	x	x	x	0	0
inflation expectations	0	x	x	0	x
monetary policy	x	x	x	x	0
money demand	x	x	0	x	x

- nonlin a21 a23 a32 a35 a41 a42 a43 a51 a52 a54
- dec frm|rect] afrml
- frm| afrml = || 1.0, 0.0, 0.0, 0.0, 0.0 | \$
- a21, 1.0, a23, 0.0, 0.0 | \$
- 0.0, a32, 1.0, 0.0, a35 | \$
- a41, a42, a43, 1.0, 0.0 | \$
- a51, a52, 0, a54, 1.0 ||



III. Structural inference from VAR's

- A. Recursive structural models
- B. Nonrecursive structural models
- C. Identification using long-run restrictions

x log of productivity
(log GDP minus log civilian
labor force)
 n log of civilian labor force

$$\mathbf{y}_t = \begin{bmatrix} \Delta x_t \\ \Delta n_t \end{bmatrix} \sim I(0)$$

VAR (reduced-form)

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \Phi_1 \mathbf{y}_{t-1} + \Phi_2 \mathbf{y}_{t-2} + \dots \\ &\quad + \Phi_p \mathbf{y}_{t-p} + \boldsymbol{\varepsilon}_t \\ E(\boldsymbol{\varepsilon}_t \boldsymbol{\varepsilon}_t') &= \boldsymbol{\Omega} \end{aligned}$$

Structural model:

$$\begin{aligned} \mathbf{B}_0 \mathbf{y}_t &= \mathbf{b}_0 + \mathbf{B}_1 \mathbf{y}_{t-1} + \mathbf{B}_2 \mathbf{y}_{t-2} \\ &\quad + \dots + \mathbf{B}_p \mathbf{y}_{t-p} + \mathbf{u}_t \\ E(\mathbf{u}_t \mathbf{u}_t') &= \mathbf{I}_2 \text{ (normalization)} \end{aligned}$$

Relation between representations:

$$\begin{aligned} \mathbf{u}_t &= \mathbf{B}_0 \boldsymbol{\varepsilon}_t \\ \boldsymbol{\Omega} &= \mathbf{B}_0^{-1} (\mathbf{B}_0^{-1})' \end{aligned}$$

Premultiply structural model,

$$\mathbf{B}(L)\mathbf{y}_t = \mathbf{b}_0 + \mathbf{u}_t$$

by $\mathbf{C}(L) = \mathbf{B}(L)^{-1}$:

$$\mathbf{y}_t = \boldsymbol{\mu} + \mathbf{C}_0\mathbf{u}_t + \mathbf{C}_1\mathbf{u}_{t-1} + \mathbf{C}_2\mathbf{u}_{t-2} + \dots$$

which gives structural MA representation

$$\mathbf{u}_t = \begin{bmatrix} u_{1t} \\ u_{2t} \end{bmatrix}$$

u_{1t} technology shock
 u_{2t} demand disturbances

Assumption: demand shocks can not have a permanent effect on productivity

$$\lim_{s \rightarrow \infty} \frac{\partial x_{t+s}}{\partial u_{2t}} = 0$$

Notice

$$\frac{\partial x_{t+s}}{\partial u_{2t}} = \frac{\partial(x_{t+s} - x_{t+s-1})}{\partial u_{2t}} + \frac{\partial(x_{t+s-1} - x_{t+s-2})}{\partial u_{2t}} + \dots + \frac{\partial(x_t - x_{t-1})}{\partial u_{2t}}$$

$$\mathbf{y}_t = \begin{bmatrix} x_t - x_{t-1} \\ n_t - n_{t-1} \end{bmatrix}$$

$$\frac{\partial(x_t - x_{t-1})}{\partial u_{2t}} = \frac{\partial y_{1t}}{\partial u_{2t}}$$

$$\mathbf{y}_t = \boldsymbol{\mu} + \mathbf{C}_0\mathbf{u}_t + \mathbf{C}_1\mathbf{u}_{t-1} + \mathbf{C}_2\mathbf{u}_{t-2} + \dots$$

$$\frac{\partial \mathbf{y}_{t+m}}{\partial \mathbf{u}_t'} = \mathbf{C}_m$$

$$\frac{\partial x_{t+s}}{\partial u_{2t}} = \frac{\partial(x_{t+s} - x_{t+s-1})}{\partial u_{2t}} + \frac{\partial(x_{t+s-1} - x_{t+s-2})}{\partial u_{2t}} + \dots + \frac{\partial(x_t - x_{t-1})}{\partial u_{2t}}$$

is given by the row 1 column 2 element of

$$\mathbf{C}_0 + \mathbf{C}_1 + \mathbf{C}_2 + \dots + \mathbf{C}_s$$

$$\lim_{s \rightarrow \infty} \frac{\partial x_{t+s}}{\partial u_{2t}} = 0$$

requires that the following matrix is lower triangular:

$$\mathbf{C}_0 + \mathbf{C}_1 + \mathbf{C}_2 + \dots = \mathbf{C}(1)$$

Goal: find structural disturbances \mathbf{u}_t that are a linear combination of the VAR innovations,

$$\mathbf{u}_t = \mathbf{H}\boldsymbol{\varepsilon}_t,$$

such that:

$$\begin{aligned} (1) \quad E(\mathbf{u}_t \mathbf{u}_t') &= \mathbf{I}_2 \\ &\Rightarrow \mathbf{H}\boldsymbol{\Omega}\mathbf{H}' = \mathbf{I}_2 \\ &\Rightarrow \boldsymbol{\Omega} = (\mathbf{H}^{-1})(\mathbf{H}^{-1})' \end{aligned}$$

$$(2) \quad \mathbf{y}_t = \boldsymbol{\mu} + \mathbf{C}(L)\mathbf{u}_t$$

$$(3) \quad \mathbf{C}(1) \text{ is lower triangular}$$

$$\begin{aligned} \Phi(L)\mathbf{y}_t &= \mathbf{c} + \boldsymbol{\varepsilon}_t \\ \boldsymbol{\varepsilon}_t &= \mathbf{H}^{-1}\mathbf{u}_t \\ &\Rightarrow \Phi(L)\mathbf{y}_t = \mathbf{c} + \mathbf{H}^{-1}\mathbf{u}_t \\ &\Rightarrow \mathbf{y}_t = \boldsymbol{\mu} + [\Phi(L)]^{-1}\mathbf{H}^{-1}\mathbf{u}_t \\ \mathbf{y}_t &= \boldsymbol{\mu} + \mathbf{C}(L)\mathbf{u}_t \\ &\Rightarrow \mathbf{C}(1) = [\Phi(1)]^{-1}\mathbf{H}^{-1} \end{aligned}$$

$$\begin{aligned} \mathbf{C}(1) &= [\Phi(1)]^{-1}\mathbf{H}^{-1} \\ \mathbf{C}(1)[\mathbf{C}(1)]' &= \\ &[\Phi(1)]^{-1}\mathbf{H}^{-1}(\mathbf{H}^{-1})' \{[\Phi(1)]^{-1}\}' \end{aligned}$$

$\mathbf{C}(1)[\mathbf{C}(1)]' =$
 $[\Phi(1)]^{-1}\Omega\{[\Phi(1)]^{-1}\}'$
 Can estimate: $\Phi(1)$ and Ω
 from VAR

Want: Lower triangular matrix
 $\mathbf{C}(1)$ such that
 $\mathbf{C}(1)[\mathbf{C}(1)]' =$
 $[\Phi(1)]^{-1}\Omega\{[\Phi(1)]^{-1}\}'$

Conclusion: $\mathbf{C}(1)$ is Cholesky
 factor of
 $[\Phi(1)]^{-1}\Omega\{[\Phi(1)]^{-1}\}'$

To get \mathbf{H} we then use fact that
 $\mathbf{C}(1) = [\Phi(1)]^{-1}\mathbf{H}^{-1}$
 $\mathbf{H} = [\mathbf{C}(1)]^{-1}[\Phi(1)]^{-1}$

Summary:

(1) Estimate VAR's by OLS

$$\mathbf{y}_t = \begin{bmatrix} \Delta x_t \\ \Delta n_t \end{bmatrix}$$

$$\mathbf{y}_t = \mathbf{c} + \hat{\Phi}_1 \mathbf{y}_{t-1} + \hat{\Phi}_2 \mathbf{y}_{t-2} + \dots + \hat{\Phi}_p \mathbf{y}_{t-p} + \hat{\varepsilon}_t$$

$$\hat{\Omega} = T^{-1} \sum_{t=1}^T \hat{\varepsilon}_t \hat{\varepsilon}_t'$$

(2) Find Cholesky factor or lower triangular matrix $\hat{\mathbf{C}}$ such that

$$\hat{\mathbf{C}}\hat{\mathbf{C}}' = \hat{\mathbf{Q}}\hat{\mathbf{Q}}'$$

$$\hat{\mathbf{Q}} = (\mathbf{I}_2 - \hat{\Phi}_1 - \hat{\Phi}_2 - \dots - \hat{\Phi}_p)^{-1}$$

(3) Technology shock and demand shock for date t are first and second elements of

$$\hat{\mathbf{u}}_t = \hat{\mathbf{B}}_0 \hat{\boldsymbol{\varepsilon}}_t$$

where

$$\hat{\mathbf{B}}_0 = \hat{\mathbf{C}}^{-1} \hat{\mathbf{Q}}$$

(4) Effect of tech shock or demand shock at date t on \mathbf{y}_{t+s} are given by first and second columns, respectively, of

$$\frac{\partial \mathbf{y}_{t+s}}{\partial \mathbf{u}_t} = \boldsymbol{\Psi}_s \mathbf{B}_0^{-1}$$

- system(model=basemod)
- variables delta_x delta_n
- lags 1 to 4
- det constant
- end(system)
- estimate

- display 'I - sum of VAR coeffs' %varlagsums
- compute Q = inv(%varlagsums)
- compute C = %decomp(Q*%sigma*tr(Q))
- compute Binvs = %varlagsums*C

$$\hat{\boldsymbol{\Omega}} = T^{-1} \sum_{t=1}^T \hat{\boldsymbol{\varepsilon}}_t \hat{\boldsymbol{\varepsilon}}_t'$$

$$\hat{\mathbf{C}} \hat{\mathbf{C}}' = \hat{\mathbf{Q}} \hat{\boldsymbol{\Omega}} \hat{\mathbf{Q}}'$$

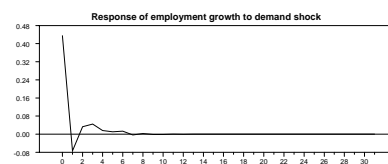
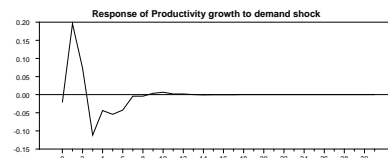
$$\hat{\mathbf{Q}} = (\mathbf{I}_2 - \hat{\boldsymbol{\phi}}_1 - \hat{\boldsymbol{\phi}}_2 - \dots - \hat{\boldsymbol{\phi}}_p)^{-1}$$

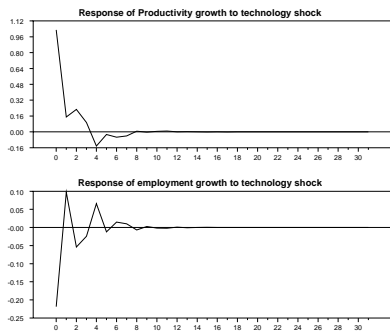
$$\hat{\mathbf{B}}_0 = \hat{\mathbf{C}}^{-1} \hat{\mathbf{Q}}$$

$$\hat{\mathbf{B}}_0^{-1} = (\mathbf{I}_2 - \hat{\boldsymbol{\phi}}_1 - \hat{\boldsymbol{\phi}}_2 - \dots - \hat{\boldsymbol{\phi}}_p) \mathbf{C}$$

$$\partial \mathbf{y}_{t+s} / \partial \mathbf{u}_t = \boldsymbol{\Psi}_s \mathbf{B}_0^{-1}$$

- declare vect[labels] implabel(neqn)
- compute inlabel=|| 'technology shock', 'demand shock' ||
- compute outlabel=|| 'Productivity growth', 'employment growth' ||
- declare rect[series] impblk(neqn,1)
- smpl 1 nsteps
- do j=1,neqn
- impulse(model=basemod, shock=%xcol(binvs,j), result=impblk) neqn nsteps
- spgraph(vfields=neqn)
- do i=1,neqn
- compute graphlabel='Response of ' +outlabel(1,i) + ' to ' +inlabel(1,j)
- graph(header=graphlabel,nodates,number=0) 1
- # impblk(i,1)
- end do i
- spgraph(done)
- end do j





Drawbacks:

(1) $\hat{Q} = (I_2 - \hat{\Phi}_1 - \hat{\Phi}_2 - \dots - \hat{\Phi}_p)^{-1}$
 is estimated poorly, sensitive to p

(2) technology shock could be temporary (e.g., delay in adoption of discovered technology)

(3) demand shock could be permanent (e.g., lost human capital)